# Which Classes of Bi-Intervals Are Closed Under Addition? Under Linear Combination? Under Other Operations?* 

Olga Kosheleva, Vladik Kreinovich, and Jonatan Contreras ${ }^{\dagger}$<br>University of Texas at El Paso<br>El Paso, TX 79968, USA<br>olgak@utep.edu, vladik@utep.edu, jmcontreras2@utep.edu


#### Abstract

In many practical situations, uncertainty with which we know each quantity is described by an interval. Techniques for processing such interval uncertainty use the fact that the sum, difference, and product of two intervals is always an interval. In some cases, the set of all possible value of a quantity is described by a bi-interval - i.e., by a union of two disjoint intervals. It is known that already the sum of two bi-intervals is not always a bi-interval. In this paper, we describe all the classes of bi-intervals which are closed under addition (i.e., for which the sum of bi-intervals is a bi-interval), closed under linear combination, and closed under other operations.


Keywords: interval uncertainty, union of two intervals, closeness under addition, closeness under linear combination, closeness under other operations
AMS subject classifications: 65G30, 65G40

## 1 Formulation of the Problem

Interval uncertainty: a brief reminder. In many real-life situations, our uncertainty about a quantity is described by an interval; see, e.g., 20.

For example, usually, the information about a physical quantity $x$ comes from measurements. As a result of the measurement, we get a value $\widetilde{x}$ which is, in general, different from the actual (unknown) value $x: \Delta x \stackrel{\text { def }}{=} \widetilde{x}-x \neq 0$. Often, the only information that we have about the measurement accuracy is the upper bound $\Delta$ on the absolute value $|\Delta x|$ of the measurement error $\Delta x$. In this case, after the measurement, the only information that we gain about the actual value $x$ is that $x$ belongs to the interval $[\widetilde{x}-\Delta, \widetilde{x}+\Delta]$; see, e.g., [20].

[^0]
## Comments.

- In some cases, we only get the lower bound. In such cases, we get an interval $[v, \infty)$. It is also possible to have intervals $(-\infty, v]$, and, of course, we can have the whole real line $(-\infty, \infty)$ corresponding to the case when we do not have any information about $x$.
- Throughout this paper, intervals will be denoted by boldface letters.

Interval computations. In many practical situations, we want to understand the state of the world and we want to predict the future state of the world. The state of the world is characterized by the values of different quantities.

Some of these quantities we can directly measure, but many others are difficult to measure directly. So, we need to be able to estimate the value $y$ of a difficult-to-directly-measure quantity. For prediction, we need to estimate the future values of different quantities $y$-and, of course, it is not possible to measure this future value now.

The usual way to perform these estimations is to use a known relation $y=$ $f\left(x_{1}, \ldots, x_{n}\right)$ between the desired quantity $y$ and one or several directly measurable quantities $x_{1}, \ldots, x_{n}$. So, to compute an estimate $\widetilde{y}$ for the desired quantity $y$, we measure the corresponding quantities $x_{i}$ and then apply the algorithm $f$ to the measurement results $\widetilde{x}_{1}, \ldots, \widetilde{x}_{n}: \widetilde{y}=f\left(\widetilde{x}_{1}, \ldots, \widetilde{x}_{n}\right)$.

As we have mentioned, the actual (unknown) value of each quantity $x_{i}$ is, in general, different from the measurement result $\widetilde{x}_{i}$. As a result, even when the dependence $y=f\left(x_{1}, \ldots, x_{n}\right)$ is known exactly, the actual value $y$ is, in general, different from the estimate $\widetilde{y}$. How different can it be? To answer this question, we need to find the range

$$
\begin{equation*}
\mathbf{y} \stackrel{\text { def }}{=} f\left(\mathbf{x}_{1}, \ldots, \mathbf{x}_{n}\right)=\left\{f\left(x_{1}, \ldots, x_{n}\right): x_{1} \in \mathbf{x}_{1}, \ldots, x_{n} \in \mathbf{x}_{n}\right\} \tag{1}
\end{equation*}
$$

of all possible values of $y=f\left(x_{1}, \ldots, x_{n}\right)$ when all we know about each quantity $x_{i}$ is that it belongs to the corresponding interval $\mathbf{x}_{i}$. The problem of computing this range is known as the problem of interval computation; see, e.g., 10, 15, 18]

Most algorithms for solving this problem use the fact that inside the computer, the only hardware supported numerical operations are elementary arithmetic operations: addition, subtraction, multiplication, and division. To be more precise, division $a / b$ is implemented as the product $a \cdot(1 / b)$, so what is hardware supported is not division itself, but the operation of taking the inverse $1 / b$. Every computation inside the computer consists of a sequence of such arithmetic operations. For example, when a computer computes the value of $\exp (x)$ or $\sin (x)$, what it actually computes is the value of the corresponding polynomial - the sum of the first few terms in the corresponding Taylor expansion.

Since elementary arithmetic operations form the basis of all computations, it is natural to first solve the interval computation problem for the cases when the corresponding function $f\left(x_{1}, x_{2}\right)$ is one these arithmetic operations: addition, subtraction, multiplication, and taking the inverse. It is known that for these functions, the range $\mathbf{y}$ is also an interval (expect, of course, for the case of the inverse $1 / b$ when the interval os possible values of $b$ contain 0 . For example, if $\mathbf{x}_{1}$ and $\mathbf{x}_{2}$ are intervals, then their sum

$$
\begin{equation*}
\mathbf{x}_{1}+\mathbf{x}_{2} \stackrel{\text { def }}{=}\left\{x_{1}+x_{2}: x_{1} \in \mathbf{x}_{1} \text { and } x_{2} \in \mathbf{x}_{2}\right\} \tag{2}
\end{equation*}
$$

is also an interval, and for every two real numbers $c_{0}$ and $c_{1}$, the set

$$
\begin{equation*}
c_{0}+c_{1} \cdot \mathbf{x}_{1} \stackrel{\text { def }}{=}\left\{c_{0}+c_{1} \cdot x_{1}: x_{1} \in \mathbf{x}_{1}\right\} \tag{3}
\end{equation*}
$$

is also an interval. The corresponding range can be computed by using simple formulas; these formulas are known as formulas of interval arithmetic.

To estimate the range (1) for a generic algorithm $f\left(x_{1}, \ldots, x_{n}\right)$ - that consists of a sequence of elementary arithmetic steps - as a very crude approximation, we can simply replace each operation with numbers with the corresponding operation with intervals. In some simple cases, this naive approach leads to reasonable results, but in general, to get meaningful results, we need to apply some sophisticated methods. In effect, these methods involve replacing the original algorithms with an equivalent one, and then kind-of applying interval arithmetic to the resulting algorithm. So, interval arithmetic still forms the basis for most current interval computations algorithms.

Linearization. In general, the problem of computing the range $f\left(\mathbf{x}_{1}, \ldots, \mathbf{x}_{n}\right)$ is NPhard already for quadratic functions $f\left(x_{1}, \ldots, x_{n}\right)$ - the simplest non-linear functions; see, e.g., 12. Crudely speaking, this means that unless $\mathrm{P}=\mathrm{NP}$ (which most computer scientists believe to be impossible), no feasible algorithm is possible that would always compute the exact range (1). In situations when we cannot compute the exact range and cannot compute a good enclosure (outer approximation) $\mathbf{Y} \supseteq \mathbf{y}$ for this range, a natural idea is to compute some approximate range.

A typical way to compute such an approximate range is to use the fact that measurements are usually reasonably accurate, i.e., the measurement errors $\Delta x_{i} \stackrel{\text { def }}{=} \widetilde{x}_{i}-x_{i}$ are reasonably small. In such situations, we can expand the desired value

$$
\begin{equation*}
f\left(x_{1}, \ldots, x_{n}\right)=f\left(\widetilde{x}_{1}-\Delta x_{1}, \ldots, \widetilde{x}_{n}-\Delta x_{n}\right) \tag{4}
\end{equation*}
$$

in Taylor series in terms of $\Delta x_{i}$ and keep only linear terms in this expansion; see, e.g., [5. 11, 25]. This way, we get the following approximate formula:

$$
\begin{equation*}
f\left(x_{1}, \ldots, x_{n}\right)=f\left(\widetilde{x}_{1}-\Delta x_{1}, \ldots, \widetilde{x}_{n}-\Delta x_{n}\right) \approx f\left(\widetilde{x}_{1}, \ldots, \widetilde{x}_{n}\right)-\sum_{i=1}^{n} \frac{\partial f}{\partial x_{i}} \cdot \Delta x_{i} \tag{5}
\end{equation*}
$$

i.e.,

$$
\begin{equation*}
f\left(x_{1}, \ldots, x_{n}\right)=a_{0}+a_{1} \cdot \Delta x_{1}+\ldots+a_{n} \cdot \Delta x_{n} \tag{6}
\end{equation*}
$$

where we denoted $a_{0} \stackrel{\text { def }}{=} f\left(\widetilde{x}_{1}, \ldots, \widetilde{x}_{n}\right)$ and

$$
\begin{equation*}
a_{i} \stackrel{\text { def }}{=}-\frac{\partial f}{\partial x_{i}}\left(\widetilde{x}_{1}, \ldots, \widetilde{x}_{n}\right) . \tag{7}
\end{equation*}
$$

Substituting $\Delta x_{i}=\widetilde{x}_{i}-x_{i}$ into this formula, we conclude that

$$
\begin{equation*}
f\left(x_{1}, \ldots, x_{n}\right) \approx c_{0}+c_{1} \cdot x_{1}+\ldots+c_{n} \cdot x_{n} \tag{8}
\end{equation*}
$$

where $c_{0}=a_{0}+\sum_{i=1}^{n} a_{i} \cdot \widetilde{x}_{i}$ and $c_{i}=-a_{i}$.
Thus, from the practical viewpoint, it is important to study the case when the function $f\left(x_{1}, \ldots, x_{n}\right)$ is a linear combination of its inputs.
Need for bi-intervals. In some cases, the set of possible value of a physical quantity is a union of two intervals; we will call such unions bi-intervals. For example, if we measured the absolute value of the velocity of an object moving along a line, and the result is $[1,2]$, but we do not know the direction of the motion, then all we know about the actual velocity is that its value is in the union $[-2,-1] \cup[1,2]$.
Comment. We consider situations in which we have two nested intervals:

- the larger interval $\mathbf{A}$ - in our case, the interval $[-2,2]$ - that contains all possible values of the corresponding quantity, and
- the smaller interval a (a subset of the larger interval A) - in our case, the interval $(-1,1)$ - which does not contain any possible value of this quantity.

To avoid possible confusion, it should be mentioned that there are other situations in which the set $S$ of possible values of a quantity is characterized by two nested intervals $\mathbf{a} \subseteq \mathbf{A}$. For example, in many practical situations, we know:

- a larger interval A that contains the unknown set $S: S \subseteq \mathbf{A}$; this set is known as an enclosure, or outer approximation, and
- a smaller interval a that is contained in the unknown set $S$ : a $\subseteq S$; this set is known as an inner approximation to the set $s$; see, e.g., [3, 6, 7, 9, 13, 14, 16, 19, 22, 23.
This situation is different from the one that we consider in this paper. Indeed, in both cases, the relation between the set $S$ and the larger interval A is the same: we have $S \subseteq \mathbf{A}$. However, the relation between the set $S$ and the smaller interval is different:
- in our case, the sets $S$ and a have no common elements: $S \cup \mathbf{a}=\emptyset$; while
- in the case when the interval $\mathbf{a}$ is an inner approximation, we have $\mathbf{a} \subseteq S$.

Multi-intervals. In some cases, there are other constrains, so, in general, the set of possible values is the union of two or intervals; see, e.g., (1) ,2, 4, 8, 17, 21, 26,
Comment. In this paper, multi-intervals (in particular, bi-intervals) will be denoted by capital letters $A, B, \ldots$.

How to process data until multi-interval uncertainty. If we know inputs $x_{i}$ with multi-interval uncertainty, how can we compute the corresponding range of possible values of $y=f\left(x_{1}, \ldots, x_{n}\right)$ ? Similarly to the case of interval computation, it is reasonable to first start with the case when the corresponding function $f\left(x_{1}, x_{2}\right)$ is one of the elementary arithmetic operations.

In this paper, we analyze the simplest non-interval case when all multi-intervals are bi-intervals. We start with the simplest elementary arithmetoc operation - addition.

Already for the simplest arithmetic operation - addition - in general, the set of bi-intervals is not closed under addition. It is easy to come with an example when the sum of two bi-intervals is not a bi-interval: e.g., it is easy to check that

$$
\begin{equation*}
([0,1] \cup[5,6])+([0,1] \cup[5,6])=[0,2] \cup[5,7] \cup[10,12] . \tag{9}
\end{equation*}
$$

A natural question. A natural question is: when is a class of bi-intervals closed under addition? under linear combination? under other operations?

In this paper, we provide answers to these questions.

## 2 Closeness Under Addition: Definitions and Results

Definition 1. For an interval $\mathbf{a}=[\underline{a}, \bar{a}]$, its width is defined as $w(\mathbf{a})=\bar{a}-\underline{a}$.

Definition 2. For two intervals $\mathbf{a}$ and $\mathbf{b}$, the lower distance $\underline{d}(\mathbf{a}, \mathbf{b})$ is the smallest possible value of $|a-b|$ when $a \in \mathbf{a}$ and $b \in \mathbf{b}$.
Comments.

- If the intervals $\mathbf{a}=[\underline{a}, \bar{a}]$ and $\mathbf{b}=[\underline{b}, \bar{b}]$ intersect, then clearly the lower distance is 0 .
- If the intervals $\mathbf{a}$ and $\mathbf{b}$ are disjoint, then, without losing generality, we can assume that $\bar{a}<\underline{b}$. Then $\underline{d}(\mathbf{a}, \mathbf{b})=\underline{b}-\bar{a}$.
- It is worth mentioning that the lower distance is different from the known Hausdorff distance

$$
\begin{gather*}
d_{H}(A, B) \stackrel{\text { def }}{=} \\
\inf \{r>0:(\forall a \in A \exists b \in B(d(a, b) \leq r)) \&(\forall b \in B \exists a \in A(d(a, b) \leq r))\} . \tag{10}
\end{gather*}
$$

Indeed, for two closed bounded sets $A$ and $B$, the Hausdorff distance is equal to 0 if and only if the sets $A$ and $B$ coincide. In contrast, the lower distance can be 0 when the intervals $\mathbf{a}$ and $\mathbf{b}$ are different but have a common point: for example, $d_{H}([0,1],[1,2])=1$ but $\underline{d}([0,1],[1,2])=0$.

Definition 3. By a bi-interval, we mean either an interval or a union of two disjoint intervals $[\underline{a}, \bar{a}] \cup[\underline{b}, \bar{b}]$.
Definition 4. Let $f\left(x_{1}, \ldots, x_{n}\right)$ be a function $\mathbb{R}^{n} \rightarrow \mathbb{R}$, and let $X_{1}, \ldots, X_{n}$ be biintervals. By the result $f\left(X_{1}, \ldots, X_{n}\right)$ of applying the function $f\left(X_{1}, \ldots, X_{n}\right)$ to biintervals $X_{i}$, we mean the range

$$
\begin{equation*}
f\left(X_{1}, \ldots, X_{n}\right) \stackrel{\text { def }}{=}\left\{f\left(x_{1}, \ldots, x_{n}\right): x_{1} \in X_{1}, \ldots, x_{n} \in X_{n}\right\} \tag{11}
\end{equation*}
$$

## Comment. In particular:

- When $f\left(x_{1}, x_{2}\right)=x_{1}+x_{2}$, we will call the set $f\left(X_{1}, X_{2}\right)$ the sum of the biintervals $X_{i}$, and denote this set by $X_{1}+X_{2}$.
- When $f\left(x_{1}, \ldots, x_{n}\right)=c_{0}+c_{1} \cdot x_{1}+\ldots+c_{n} \cdot x_{n}$ for some constants $c_{i}$, we will call the set $f\left(X_{1}, \ldots, X_{n}\right)$ the linear combination of the bi-intervals $X_{i}$, and denote this set by $c_{0}+c_{1} \cdot X_{1}+\ldots+c_{n} \cdot X_{n}$.
Definition 5. We say that a bi-interval is close if it is either an interval, or the union $\mathbf{a} \cup \mathbf{b}$ of two disjoint intervals for which $\underline{d}(\mathbf{a}, \mathbf{b}) \leq \max (w(\mathbf{a}), w(\mathbf{b}))$.
Comments. Since every infinite or semi-infinite interval has infinite width, this implies that every bi-interval in which one of the intervals is infinite or semi-infinite is close. In particular, every interval of the type $(-\infty, \bar{a}] \cup[\underline{b}, \infty)$ is close.
Proposition 1. A bi-interval $\mathbf{a} \cup \mathbf{b}$ is close if and only if its sum with itself is also a bi-interval.
Comment. For reader's convenience, all the proofs are placed in the special Proofs section.
Proposition 2. The sum of two close bi-intervals is always close.
These two results lead to the following characterization of all classes of bi-intervals which are closed under addition:
Theorem 1. Let $\mathcal{C}$ be a class of bi-intervals which is closed under addition. Then every bi-interval from the class $\mathcal{C}$ is close.
Theorem 2. The class of all close bi-intervals is closed under addition.


## 3 Closeness Under Linear Combination

Proposition 3. For each close bi-interval $A=\mathbf{a} \cup \mathbf{b}$ and for all $c_{0}$ and $c_{1}$, the bi-interval

$$
\begin{equation*}
c_{0}+c_{1} \cdot A=\left(c_{0}+c_{1} \cdot \mathbf{a}\right) \cup\left(c_{0}+c_{1} \cdot \mathbf{b}\right) \tag{12}
\end{equation*}
$$

is also close.
Together with closeness under addition, this result leads to the following characterization of all classes of bi-intervals which are closed under linear combination.

Theorem 3. Let $\mathcal{C}$ be a class of bi-intervals which is closed under linear combination. Then every bi-interval from the class $\mathcal{C}$ is close.

Theorem 4. The class of all close bi-intervals is closed under linear combination.

## 4 What About Other Operations

The following result shows that linear combinations are the only operations that preserve closeness of bi-intervals.

Theorem 5. For a continuously differentiable function $f\left(x_{1}, \ldots, x_{n}\right)$, the following two conditions are equivalent:

- for any close bi-intervals $X_{1}, \ldots, X_{n}$, the set $f\left(X_{1}, \ldots, X_{n}\right)$ is also a close biinterval;
- the function $f\left(x_{1}, \ldots, x_{n}\right)$ is linear, i.e.,

$$
\begin{equation*}
f\left(x_{1}, \ldots, x_{n}\right)=c_{0}+c_{1} \cdot x_{1}+\ldots+c_{n} \cdot x_{n} \tag{13}
\end{equation*}
$$

for some constants $c_{i}$.

## 5 Proofs

Proof of Proposition 1. Let us prove that a bi-interval $\mathbf{a} \cup \mathbf{b}$ is close if and only if its sum with itself is also a bi-interval.

If the bi-interval is an interval, then its sum with itself is also an interval hence a bi-interval. So, it is sufficient to consider the case when the intervals $\mathbf{a}=[\underline{a}, \bar{a}]$ and $\mathbf{b}=[\underline{b}, \bar{b}]$ are disjoint. In this case, without losing generality, we can assume that $\bar{a}<\underline{b}$.

The sum $S$ of the bi-interval with itself has the following form (in which we sorted the three component intervals by their lower bounds):

$$
\begin{equation*}
[2 \underline{a}, 2 \bar{a}] \cup[\underline{a}+\underline{b}, \bar{a}+\bar{b}] \cup[2 \underline{b}, 2 \bar{b}] . \tag{14}
\end{equation*}
$$

If

$$
\begin{equation*}
2 \bar{a}<\underline{a}+\underline{b} \tag{15}
\end{equation*}
$$

and

$$
\begin{equation*}
\bar{a}+\bar{b}<2 \underline{b}, \tag{16}
\end{equation*}
$$

then this sum is a union of three disjoint intervals, i.e., not a bi-interval; otherwise, it is a union of two (or one) intervals, i.e., a bi-interval.

The inequality (15) is equivalent to $\bar{a}-\underline{a}<\underline{b}-\bar{a}$, i.e., to $w(\mathbf{a})<\underline{d}(\mathbf{a}, \mathbf{b})$. Similarly, the inequality (16) is equivalent to $\bar{b}-\underline{b}<\underline{b}-\bar{a}$, i.e., to $w(\mathbf{b})<\underline{d}(\mathbf{a}, \mathbf{b})$. Thus, both inequalities are satisfied if and only if $\max (w(\mathbf{a}), w(\mathbf{b}))<\underline{d}(\mathbf{a}, \mathbf{b})$, i.e., exactly if and only if the bi-interval is not close.

The proposition is proven.
Proof of Proposition 2. Let us prove that the sum of two close bi-intervals is always close.

Indeed, when we add intervals, their width increases (or at least not decreases), while the lower distance only decreases (or at least remains the same), thus the inequality remains. The proposition is proven.
Proof of Proposition 3. Let us prove that for each close bi-interval $\mathbf{a} \cup \mathbf{b}$ and for all $c_{0}$ and $c_{1}$, the bi-interval $\left(c_{0}+c_{1} \cdot \mathbf{a}\right) \cup\left(c_{0}+c_{1} \cdot \mathbf{b}\right)$ is also close.

Indeed, a shift by $c_{0}$ does not change the lower distance and the widths, and multiplication by $c_{1}$ multiplies all these values by $\left|c_{1}\right|$. Thus, for the new intervals, the inequality describing closeness still remains.

The proposition is proven.

## Proof of Theorem 5.

$1^{\circ}$. We have already proven that a linear combination of close bi-intervals is a close bi-interval. So, to prove our theorem, it is sufficient to prove that if some continuously differentiable function $f\left(x_{1}, \ldots, x_{n}\right)$ always transforms close bi-intervals into a close bi-interval, this means that this function is linear.

So let us assume that $f\left(x_{1}, \ldots, x_{n}\right)$ is such a function, and let us prove that this function is linear.
$2^{\circ}$. Let us start with the case when $n=1$, i.e., when $f\left(x_{1}\right)$ is a continuously differentiable function of one variable.

If the derivative $f^{\prime}\left(x_{1}\right)$ is always equal to 0 , this means that this function is a constant - and is, therefore, a linear function. Let us now consider the case when the function is not constant, i.e., when there exist values $x_{1}$ for which $f^{\prime}\left(x_{1}\right) \neq 0$. Let us pick any such value $x_{0}$. Without losing generality, let us assume that $f^{\prime}\left(x_{0}\right)>0$; the case when $f^{\prime}\left(x_{0}\right)<0$ can be treated the same way.

Since the derivative $f^{\prime}\left(x_{1}\right)$ is continuous, from the fact that $f^{\prime}\left(x_{0}\right)>0$ it follow that the derivative is positive in some open neighborhood $N$ of the point $x_{0}$. So, in this neighborhood $N$, the function $f\left(x_{1}\right)$ is strictly increasing. For an increasing function $f\left(x_{1}\right)$, its range $f([\underline{x}, \bar{x}])$ on any interval is simply equal to $[f(\underline{x}), f(\bar{x})]$.

For any three points $x-h, x$, and $x+h$ from the neighborhood $N$, the bi-intervals $[x-h, x-h] \cup[x, x+h]$ and $[x-h, x] \cup[x+h, x+h]$ are close. The image

$$
\begin{equation*}
f([x-h, x-h] \cup[x, x+h]) \tag{17}
\end{equation*}
$$

of the first close bi-interval is thus equal to $[f(x-h), f(x-h)] \cup[f(x), f(x+h])$. This is clearly a bi-interval. The fact that this bi-interval is close means that

$$
\begin{equation*}
f(x)-f(x-h) \leq f(x+h)-f(x) . \tag{18}
\end{equation*}
$$

The fact that the image

$$
\begin{equation*}
f([x-h, x] \cup[x+h, x+h])=[f(x-h, f(x)],[f(x+h, f(x+h)] \tag{19}
\end{equation*}
$$

is close means that

$$
\begin{equation*}
f(x+h)-f(x) \leq f(x)-f(x-h) \tag{20}
\end{equation*}
$$

From the inequalities (18) and (20), we conclude that

$$
\begin{equation*}
f(x+h)-f(x)=f(x)-f(x-h) \tag{21}
\end{equation*}
$$

In particular, this means that for any value $a$ and for all $k$ for which $a+k \cdot h \in N$, we have

$$
\begin{gather*}
f(a+h)-f(a)=f(a+2 h)-f(a+h)=\ldots= \\
f(a+k \cdot h)-f(a+(k-1) \cdot h) \tag{22}
\end{gather*}
$$

If we denote this common difference by $d \stackrel{\text { def }}{=} f(a+h)-f(a)$, we conclude that $f(a+$ $i \cdot h)=f(a)+i \cdot d$, i.e., that $f(a+\Delta)=f(a)+(d / h) \cdot \Delta$ for all values $\Delta$ of the type $\Delta=i \cdot h$. In the limit $h \rightarrow 0$, we conclude that the function $f\left(x_{1}\right)$ is linear in the neighborhood $N$. Thus, in this neighborhood, the derivative $f^{\prime}\left(x_{1}\right)$ is constant.

This is true for every neighborhood in which the derivative is positive. Since the derivative is continuous, it cannot jump to 0 or to a negative number, so the derivative will be everywhere positive and thus, everywhere constant. So, the function $f\left(x_{1}\right)$ is indeed linear.
$3^{\circ}$. Let us now consider the case when $n=2$, i.e., when $f\left(x_{1}, x_{2}\right)$ is a function of two variables. By taking $X_{2}=\left[x_{2}, x_{2}\right]$, we conclude, from Part 2 of this proof, that for every $x_{2}$, the function $x_{1} \rightarrow f\left(x_{1}, x_{2}\right)$ is linear, i.e., that

$$
\begin{equation*}
f\left(x_{1}, x_{2}\right)=c_{0}\left(x_{2}\right)+c_{1}\left(x_{2}\right) \cdot x_{1} \tag{23}
\end{equation*}
$$

for some coefficients $c_{0}\left(x_{2}\right)$ and $c_{1}\left(x_{2}\right)$ which are, in general, different for different values $x_{2}$. Similarly, we can conclude that

$$
\begin{equation*}
f\left(x_{1}, x_{2}\right)=a_{0}\left(x_{1}\right)+a_{1}\left(x_{1}\right) \cdot x_{2} \tag{24}
\end{equation*}
$$

Equating the two expressions for $f\left(x_{1}, x_{2}\right)$, we conclude that for all $x_{1}$ and $x_{2}$, we have

$$
\begin{equation*}
c_{0}\left(x_{2}\right)+c_{1}\left(x_{2}\right) \cdot x_{1}=a_{0}\left(x_{1}\right)+a_{1}\left(x_{1}\right) \cdot x_{2} . \tag{25}
\end{equation*}
$$

Let us consider two possible cases:

- when the function $c_{1}\left(x_{2}\right)$ is constant, and
- when this function is not constant.
$3.1^{\circ}$. If the function $c_{1}\left(x_{2}\right)$ is constant, i.e., if $c_{1}\left(x_{2}\right)=c_{1}$ for all $x_{2}$, then from (25) for $x_{1}=0$, we conclude that

$$
\begin{equation*}
c_{0}\left(x_{2}\right)=a_{0}(0)+a_{1}(0) \cdot x_{2} . \tag{26}
\end{equation*}
$$

Substituting this expression for $c_{0}\left(x_{2}\right)$ and $c_{1}\left(x_{2}\right)=c_{1}$ into the formula (N3), we conclude that

$$
\begin{equation*}
f\left(x_{1}, x_{2}\right)=a_{0}(0)+a_{1}(0) \cdot x_{2}+c_{1} \cdot x_{1} \tag{27}
\end{equation*}
$$

i.e., that $f\left(x_{1}, x_{2}\right)$ is a linear function of two variables.
$3.2^{\circ}$. Let us now consider the case when the function $c_{1}\left(x_{2}\right)$ is not a constant, i.e., when there exist two values $a_{2}$ and $b_{2}$ for which $c_{1}\left(a_{2}\right) \neq c_{1}\left(b_{2}\right)$. Substituting $x_{2}=a_{2}$ and $x_{2}=b_{2}$ into the formula (25), we get the following two equalities:

$$
\begin{equation*}
c_{0}\left(a_{2}\right)+c_{1}\left(a_{2}\right) \cdot x_{1}=a_{0}\left(x_{1}\right)+a_{1}\left(x_{1}\right) \cdot a_{2} \tag{28}
\end{equation*}
$$

$$
\begin{equation*}
c_{0}\left(b_{2}\right)+c_{1}\left(b_{2}\right) \cdot x_{1}=a_{0}\left(x_{1}\right)+a_{1}\left(x_{1}\right) \cdot b_{2} \tag{29}
\end{equation*}
$$

We can view this as a system of two linear equations with two unknowns $a_{0}\left(x_{1}\right)$ and $a_{1}\left(x_{1}\right)$. Subtracting these two equations, we conclude that

$$
\begin{equation*}
a_{1}\left(x_{1}\right) \cdot\left(a_{2}-b_{2}\right)=\left(c_{0}\left(a_{2}\right)-c_{0}\left(b_{2}\right)\right)+\left(c_{1}\left(a_{2}\right)-c_{1}\left(b_{2}\right)\right) \cdot x_{1} \tag{30}
\end{equation*}
$$

hence, that

$$
\begin{equation*}
a_{1}\left(x_{1}\right)=\frac{c_{0}\left(a_{2}\right)-c_{0}\left(b_{2}\right)}{a_{2}-b_{2}}+\frac{c_{0}\left(a_{2}\right)-c_{0}\left(b_{2}\right)}{a_{2}-b_{2}} \cdot x_{1} \tag{31}
\end{equation*}
$$

So, $a_{1}\left(x_{1}\right)$ is a linear function of $x_{1}$. Now, from (28), we conclude that

$$
\begin{equation*}
a_{0}\left(x_{1}\right)=c_{0}\left(a_{2}\right)+c_{1}\left(a_{2}\right) \cdot x_{1}-a_{1}\left(x_{1}\right) \cdot a_{2} \tag{32}
\end{equation*}
$$

and thus, that $a_{0}\left(x_{1}\right)$ is also a linear function.
Substituting the linear expressions for $a_{0}\left(x_{1}\right)$ and $a_{1}\left(x_{1}\right)$ into the expression (N4), we conclude that the function $f\left(x_{1}, \ldots, x_{n}\right)$ is bilinear, i.e., has the form

$$
\begin{equation*}
f\left(x_{1}, x_{2}\right)=f_{0}+f_{1} \cdot x_{1}+f_{2} \cdot x_{2}+f_{12} \cdot x_{1} \cdot x_{2} \tag{33}
\end{equation*}
$$

for some constant $f_{i}$.
$4^{\circ}$. Similarly, we can prove that for all $n$, the function $f\left(x_{1}, \ldots, x_{n}\right)$ is multi-linear, i.e., has the form

$$
\begin{gather*}
f\left(x_{1}, \ldots, x_{n}\right)=f_{0}+\sum_{i=1}^{n} f_{i} \cdot x_{i}+\sum_{i_{1}<i_{2}} f_{i_{1} i_{2}} \cdot x_{i_{1}} \cdot x_{i_{2}}+\sum_{i_{1}<i_{2}<i_{3}} f_{i_{1} i_{2} i_{3}} \cdot x_{i_{1}} \cdot x_{i_{2}} \cdot x_{i_{3}}+\ldots+ \\
f_{1 \ldots n} \cdot x_{1} \cdot \ldots \cdot x_{n} \tag{34}
\end{gather*}
$$

$5^{\circ}$. Let us prove that for $n=2$, the function $f\left(x_{1}, x_{2}\right)$ must be linear. We will prove it by contradiction.

Indeed, let us assume that the function $f\left(x_{1}, x_{2}\right)$ is not linear, i.e., that it has the form (33) with $f_{12} \neq 0$. Our assumption about this function is that for all close bi-intervals $X_{1}$ and $X_{2}$, the range $f\left(X_{1}, X_{2}\right)$ is also a close bi-interval. Since a multiplication by a constant does not change closeness, this implies that the intervals $g\left(X_{1}, X_{2}\right)=f_{12}^{-1} \cdot f\left(X_{1}, X_{2}\right)$ is also close, where

$$
\begin{equation*}
g\left(x_{1}, x_{2}\right) \stackrel{\text { def }}{=} f_{12}^{-1} \cdot f\left(x_{1}, x_{2}\right)=g_{0}+g_{1} \cdot x_{1}+g_{2} \cdot x_{2}+x_{1} \cdot x_{2} \tag{35}
\end{equation*}
$$

and $g_{i} \stackrel{\text { def }}{=} f_{12}^{-1} \cdot f_{i}$. The expression for $g\left(x_{1}, x_{2}\right)$ can be rewritten as

$$
\begin{equation*}
g\left(x_{1}, x_{2}\right)=\left(x_{1}+g_{2}\right) \cdot\left(x_{2}+g_{1}\right)+\left(g_{0}-g_{1} \cdot g_{2}\right) \tag{36}
\end{equation*}
$$

Since adding a constant does not change closeness, this implies that the set

$$
\begin{equation*}
\left(X_{1}+g_{2}\right) \cdot\left(X_{2}+g_{1}\right) \tag{37}
\end{equation*}
$$

is also a close bi-interval.
For any two close bi-intervals $Y_{1}$ and $Y_{2}$, the bi-intervals $X_{1}=Y_{1}-g_{2}$ and $X_{2}=$ $Y_{2}-g_{1}$ are also close. Thus, the range

$$
\begin{equation*}
\left(X_{1}+g_{2}\right) \cdot\left(X_{2}+g_{1}\right)=\left(\left(Y_{1}-g_{1}\right)+g_{1}\right) \cdot\left(\left(Y_{2}-g_{1}\right)+g_{1}\right)=Y_{1} \cdot Y_{2} \tag{38}
\end{equation*}
$$

is also a close bi-interval. So, we conclude that the product of two close bi-intervals should also be a close bi-interval.

But this is not always true: e.g., for close bi-intervals $Y_{1}=Y_{2}=[-0.4,-0.4] \cup$ [0.6, 1.6], the product $Y_{1} \cdot Y_{2}$ is not a bi-interval: it is the union of three disjoint intervals:

$$
\begin{equation*}
Y_{1} \cdot Y_{2}=[-0.64,-0.24] \cup[0.16,0.16] \cup[0.36,2.56] . \tag{39}
\end{equation*}
$$

The contradiction shows that we cannot have $f_{12} \neq 0$. So, $f_{12}=0$, and the function $f\left(x_{1}, x_{2}\right)$ is linear.
$6^{\circ}$. Similarly to Part 5 of this proof, we can conclude that in the multi-linear function $f\left(x_{1}, \ldots, x_{n}\right)$, all the coefficients $f_{i_{1} i_{2}}$ should be equal to 0 .

Let us show that all the terms $f_{i_{1} i_{2} i_{3}}$ should also be equal to 0 . Indeed, if $f_{i_{1} i_{2} i_{3}} \neq 0$ for some $i_{j}$, then substituting $x_{i_{3}}=1$ and $x_{i}=0$ for all $i$ different from $i_{j}$ into the general expression for a multi-linear function, we get a function of two variables

$$
\begin{equation*}
f\left(x_{i_{1}}, x_{i_{3}}\right)=f_{0}+f_{i_{1}} \cdot x_{i_{1}}+f_{2} \cdot x_{i_{2}}+f_{i_{3}}+f_{i_{1} i_{2} i_{3}} \cdot x_{i_{1}} \cdot x_{i_{2}} \tag{40}
\end{equation*}
$$

This function of two variables should also transform close bi-intervals into close biintervals, but we have already shown that, when we have a non-zero coefficient at the product $x_{i_{1}} \cdot x_{i_{2}}$, this is not possible.

Similarly, we can prove that all other non-linear coefficients $f_{i_{1} \ldots i_{k}}$ should also be equal to 0 , and thus, that the function $f\left(x_{1}, \ldots, x_{n}\right)$ is indeed linear. The theorem is proven.

## 6 Conclusions and Remaining Open Questions

Conclusions. In data processing, it is important to analyze how uncertainty in the inputs affects the results of data processing. In the case of interval uncertainty, this analysis is simplified by the fact that the sum, difference, and product of two intervals is also an interval. In the linearized case, what is important is that the linear combination of intervals is also an interval.

In some practical situations, the uncertainty in some (or all) inputs is characterized not by a single interval, but by a union of two (or more) intervals. Such unions are known as multi-intervals, or, in the same of a union of two intervals, bi-intervals. It is known that already the set of bi-intervals is not closed under addition. A natural question is: what classes of bi-intervals are closed under addition? under linear combination? under other operations?

In this paper, we give a full characterization of all classes of bi-intervals which are closed under addition and under linear combination. Namely, for each corresponding bi-interval, the gap between the two united intervals cannot exceed the largest width of the two intervals. We can such bi-intervals close. We also show that the class of all close bi-intervals is not closed under any non-linear operation (such as multiplication).

## Remaining open questions.

- We proved that the only operations preserving the class of all close bi-intervals are linear ones. A natural question is: is there a subclass of the class of all close bi-intervals which is closed under addition and multiplication? under addition, multiplication, and inverse $1 / x$ ?
- What if instead of bi-intervals - i.e., unions of at most two disjoint intervals we consider tri-intervals, i.e., unions of no more than 3 disjoint intervals? What if we consider $n$-intervals - unions of no more than $n$ disjoint intervals?


## References

[1] H. Batnini, C. Michel, and M. Rueher, "Mind the gaps: a new splitting strategy for consistency techniques", Proceedings of the 11th International Conference on Principles and Practice of Constraint Programming CP'2005, Sitges, Spain, October 1-5, 2005.
[2] G. Chabert, G. Trombettoni, and B. Neveu, "Box-set consistency for intervalbased constraint problems", Proceedings of the 2005 AMC Symposium on Applied Computing SAC'05, Santa Fe, New Mexico, March 13-17, 2005, Santa Fe, New Mexico, pp. 1439-1443.
[3] S. Chevillard, "Efficient and accurate computation of upper bounds of approximation errors", Theoretical Computer Science, 2011. Vol. 412, No. 16, pp. 1523-1543.
[4] H. Collavizza, F. Delobel, and M. Rueher, "Comparing Partial Consistencies", Reliable Computing, 1999, Vol. 5, No. 3, pp. 213-228.
[5] R. Feynman, R. Leighton, and M. Sands, Feynman Lectures on Physics, Basic Books, New York, 2005.
[6] A. Goldsztejn, "A right-preconditioning process for the formal-algebraic approach to inner and outer estimation of ae-solution sets", Reliable Computing, 2005, Vol. 11, No. 6, pp. 443-478
[7] A. Goldsztejn and L. Jaulin, "Inner approximation of the range of vector-valued functions", Reliable Computing, 2010, Vol. 14, pp. 1-23.
[8] L. Granvilliers and F. Benhamou, "RealPaver: an interval solver using constraint satisfaction techniques", ACM Transactions on Mathematical Software, 2006, Vol. 32, No. 1, pp. 138-156.
[9] L. Jaulin, "Inner and outer set-membership state estimation", Reliable Computing, 2016, Vol. 18, pp. 47-55.
[10] L. Jaulin, M. Kiefer, O. Dicrit, and E. Walter, Applied Interval Analysis, Springer, London, 2001.
[11] V. Kreinovich, "Interval computations and interval-related statistical techniques: estimating uncertainty of the results of data processing and indirect measurements", In: F. Pavese, W. Bremser, A. Chunovkina, N. Fisher, and A. B. Forbes (eds.), Advanced Mathematical and Computational Tools in Metrology and Testing AMTCM'X, World Scientific, Singapore, 2015, pp. 38-49.
[12] V. Kreinovich, A. Lakeyev, J. Rohn, and P. Kahl, Computational Complexity and Feasibility of Data Processing And Interval Computations, Kluwer, Dordrecht, 1998.
[13] V. Kreinovich, V. M. Nesterov, and N. A. Zheludeva, "Interval methods that are guaranteed to underestimate (and the resulting new justification of Kaucher arithmetic)", Reliable Computing, 1996, Vol. 2, No. 2, pp. 119-124.
[14] L. Kupriyanova, "Inner estimation of the united solution set of interval linear algebraic system", Reliable Computing, 1995, Vol. 1, No. 1, pp. 15-32.
[15] G. Mayer, Interval Analysis and Automatic Result Verification, de Gruyter, Berlin, 2017.
[16] D. Monnet, J. Ninin, and L. Jaulin, "Computing an inner and an outer approximation of the viability kernel", Reliable Computing, 2016, Vol. 18, pp. 138-148.
[17] T. Montanher, F. Domes, H. Schichl, and A. Neumaier, "Using interval unions to solve linear systems of equations with uncertainties", BIT Numerical Mathematics, 2017, Vol. 57, No. 3, pp. 901-926.
[18] R. E. Moore, R. B. Kearfott, and M. J. Cloud, Introduction to Interval Analysis, SIAM, Philadelphia, 2009.
[19] O. Mullier, E. Goubault, M.Kieffer, and S. Putot, "General Inner Approximation of Vector-valued Functions", Reliable Computing, 2013, Vol. 18, pp. 117-143.
[20] S. G. Rabinovich, Measurement Errors and Uncertainties: Theory and Practice, Springer, New York, 2005.
[21] H. Schichl, F. Domes, T. Montanher, and K. Kofler, "Interval unions", BIT Numerical Mathematics, 2017, Vol. 57, pp. 531-556.
[22] I. A. Sharaya, "On maximal inner estimation of the solution sets of linear systems with interval parameters", Reliable Computing, 2001, Vol. 7, No. 5, pp. 409-424.
[23] S. P. Shary, "Algebraic approach to the interval linear static identification, tolerance, and control problems, or One more application of Kaucher arithmetic", Reliable Computing, 1996, Vol. 2, No. 1, pp. 3-34.
[24] V. Stahl, "Error reduction of the Taylor centered form by half and an inner estimation of the range", Reliable Computing, 1997, Vol. 3, No. 4, pp. 411-420.
[25] K. S. Thorne and R. D. Blandford, Modern Classical Physics: Optics, Fluids, Plasmas, Elasticity, Relativity, and Statistical Physics, Princeton University Press, Princeton, New Jersey, 2017.
[26] A. G. Yakovlev, "Computer arithmetic of multiintervals", Problems of Cybernetics, 1987, pp. 66-81.


[^0]:    *Submitted: June 27, 2020; Revised: May 29, 2021; Accepted: June 3, 2021.
    ${ }^{\dagger}$ This work was supported in part by the National Science Foundation grants 1623190 (A Model of Change for Preparing a New Generation for Professional Practice in Computer Science) and HRD-1242122 (Cyber-ShARE Center of Excellence).
    The authors are greatly thankful to the anonymous referees for valuable suggestions.

